Math 3100

#### Section 1.3: Vector Equations

We defined

- vectors in  $\mathbb{R}^n$ ,
- the operations of scalar multiplication and vector addition in  $\mathbb{R}^n$ ,
- vector equivalence,
- a linear combination of vectors, and
- Span.

#### We introduced notation:

Letting 
$$\mathbf{a}_1 = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}$$
,  $\mathbf{a}_2 = \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix}$ , ...,  $\mathbf{a}_n = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$  be *n* vectors in  $\mathbb{R}^m$ , we can write an  $m \times n$  matrix having these vectors as columns

$$[\mathbf{a}_1 \quad \mathbf{a}_2 \quad \cdots \quad \mathbf{a}_n] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}.$$

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### Span: Three Equivalent Things

- 1. If **b** is in Span{ $\mathbf{v}_1, \ldots, \mathbf{v}_p$ }, then  $\mathbf{b} = c_1 \mathbf{v}_1 + \cdots + c_p \mathbf{v}_p$ .
- 2. From the previous result, we know this is equivalent to saying that the vector equation

$$x_1\mathbf{v}_1+\cdots+x_p\mathbf{v}_p=\mathbf{b}$$

has a solution.

3. This is in turn the same thing as saying the linear system with augmented matrix  $[\mathbf{v}_1 \cdots \mathbf{v}_p \mathbf{b}]$  is consistent.

### Examples

Let 
$$\mathbf{a}_1 = \begin{bmatrix} 1\\1\\2 \end{bmatrix}$$
, and  $\mathbf{a}_2 = \begin{bmatrix} -1\\4\\-2 \end{bmatrix}$ .  
(a) Determine if  $\mathbf{b} = \begin{bmatrix} 4\\2\\1 \end{bmatrix}$  is in Span $\{\mathbf{a}_1, \mathbf{a}_2\}$ .

We found that **b** is not in Span $\{a_1, a_2\}$ . We did this by setting up the matrix and obtaining an rref:

$$[\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{b}] \quad (rref) \longrightarrow \quad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The last column is a pivot column. The system is inconsistent.

(b) Determine if 
$$\mathbf{b} = \begin{bmatrix} 5 \\ -5 \\ 10 \end{bmatrix}$$
 is in Span $\{\mathbf{a}_1, \mathbf{a}_2\}$ .  
Do there exist scalars  $C_1, C_2$  such that  
 $C_1 \vec{a}_1 + C_2 \vec{a}_2 = \vec{b}$ ?  
We can answer by considering the matrix  $(\vec{a}_1, \vec{a}_2, \vec{b})$ .  
 $\begin{bmatrix} \vec{a}_1 \vec{a}_2 \ \vec{b} \end{bmatrix} = \begin{bmatrix} 1 & -1 & S \\ 1 & y & -S \\ 2 & -2 & 10 \end{bmatrix} \xrightarrow{\text{Tref}} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$   
The 3<sup>C2</sup> column is not a pluot column. Hence,

the system is consistent. Is is in Span (a, a, the From the rref, the system is equivalent to c, = 3 (z = -2  $\begin{array}{c} |c_{1} + 0c_{2} = 3 \\ 0c_{1} + |c_{2} = -2 \end{array} \right\} \Rightarrow$ 0(1 + 0(2 = 0)Note  $3\vec{a}_{1} + (-2)\vec{a}_{2} = 3\begin{bmatrix} 1\\ 1\\ 2\end{bmatrix} - 2\begin{bmatrix} -1\\ 4\\ -2\end{bmatrix} = \begin{bmatrix} 5\\ -5\\ 10\end{bmatrix}$ 

### Another Example

Give a geometric description of the subset of  $\mathbb{R}^2$  given by Span  $\left\{ \begin{bmatrix} 1\\0 \end{bmatrix} \right\}$ . If  $\tilde{h}$  is in Span  $\left\{ \begin{bmatrix} 1\\0 \end{bmatrix} \right\}$  then  $\vec{u} = C \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} C \\ 0 \end{bmatrix}$  for some real number C. Like a traditional point, this is (C, O) for some real number C.

This is the X-axis.

## Span $\{\mathbf{u}\}$ in $\mathbb{R}^3$

If u is any nonzero vector in  $\mathbb{R}^3,$  then  $\text{Span}\{u\}$  is a line through the origin parallel to u.

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# $\text{Span}\{\boldsymbol{u},\boldsymbol{v}\} \text{ in } \mathbb{R}^3$

If **u** and **v** are nonzero, and nonparallel vectors in  $\mathbb{R}^3$ , then Span $\{\mathbf{u}, \mathbf{v}\}$  is a plane containing the origin parallel to both vectors.

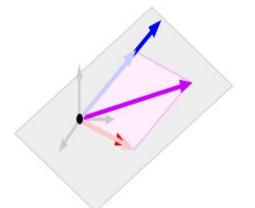


Figure: The red and blue vectors are  $\mathbf{u}$  and  $\mathbf{v}$ . The plane is the collection of all possible linear combinations. (A purple representative is shown.)

#### Example

Let  $\mathbf{u} = (1, 1)$  and  $\mathbf{v} = (0, 2)$  in  $\mathbb{R}^2$ . Show that for every pair of real numbers *a* and *b*, that (a, b) is in Span $\{\mathbf{u}, \mathbf{v}\}$ .

we need to show that for any (a,b), there exist weights X, and X2 such that  $X_1 \vec{u} + X_2 \vec{v} = \begin{bmatrix} A \\ B \end{bmatrix}$ We can use an augmented motion [II V [B]]  $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & b \end{bmatrix} \xrightarrow{P_1 + R_2 \to R_2} R_2$ イロン イボン イヨン 「ヨ

$$\begin{bmatrix} 1 & 0 & a \\ 0 & 2 & b-a \end{bmatrix} \xrightarrow{1}{2}R_2 \Rightarrow R_2$$

$$\begin{bmatrix} 1 & 0 & a \\ 0 & 1 & \frac{b-a}{2} \end{bmatrix}$$

$$\begin{array}{c} \text{The last column is not a} \\ \text{pivot column for any (a,b).} \end{array}$$

$$\begin{array}{c} \text{The system is consistant for all (a,b).} \\ \text{That is, (a,b) is in Span {U,V}.} \end{array}$$

More over,  

$$A \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \frac{b \cdot a}{z} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} A \\ b \end{bmatrix}$$

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